ASSIGNMENT 4

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

PROGRAM:

|  |
| --- |
| int t=2; |
|  | int e=3; |
|  | void setup() |
|  | { |
|  | Serial.begin(9600); |
|  | pinMode(t,OUTPUT); |
|  | pinMode(e,INPUT); |
|  | pinMode(12,OUTPUT); |
|  | } |
|  | void loop() |
|  | { |
|  | //ultrasonic sensor |
|  | digitalWrite(t,LOW); |
|  | digitalWrite(t,HIGH); |
|  | delayMicroseconds(10); |
|  | digitalWrite(t,LOW); |
|  | float dur=pulseIn(e,HIGH); |
|  | float dis=(dur\*0.0343)/2; |
|  | Serial.print("Distance is: "); |
|  | Serial.println(dis); |
|  | //LED ON |
|  | if(dis>=100) |
|  | { |
|  | digitalWrite(8,HIGH); |
|  | digitalWrite(7,HIGH); |
|  | } |
|  |  |
|  | //Buzzer For ultrasonic Sensor |
|  | if(dis>=100) |
|  | { |
|  | for(int i=0; i<=30000; i=i+10) |
|  | { |
|  | tone(12,i); |
|  | delay(1000); |
|  | noTone(12); |
|  | delay(1000); |
|  | } |
|  | } |
|  |  |
|  | //Temperate Sensor |
|  | double a= analogRead(A0); |
|  | double t=(((a/1024)\*5)-0.5)\*100; |
|  | Serial.print("Temp Value: "); |
|  | Serial.println(t); |
|  | delay(1000); |
|  |  |
|  | //LED ON |
|  | if(t>=100) |
|  | { |
|  |  |
|  | digitalWrite(8,HIGH); |
|  | digitalWrite(7,HIGH); |
|  | } |
|  |  |
|  | //Buzzer for Temperature Sensor |
|  | if(t>=100) |
|  | { |
|  | for(int i=0; i<=30000; i=i+10) |
|  | { |
|  | tone(12,i); |
|  | delay(1000); |
|  | noTone(12); |
|  | delay(1000); |
|  | } |
|  | } |
|  |  |
|  | //LED OFF |
|  | if(t<100) |
|  | { |
|  | digitalWrite(8,LOW); |
|  | digitalWrite(7,LOW); |
|  | } |
|  | } |